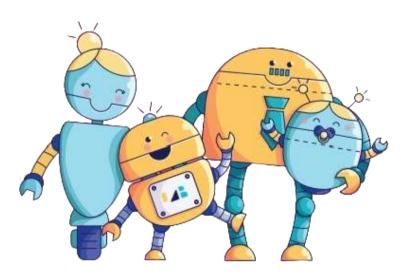


# THE LAB KINDER

Early Childhood is a wonderful time to spark a kid's interest in Coding, Robotics, Engineering. Young children are curious about the world around them, and today that would include technology. But how best to promote positive, creative and educational engagement with technology? We got the answer for you.



## MEET THE SENIOR TEAM



### DR. OKA KURNIAWAN

Dr. Oka is a Senior Lecturer for Singapore University of Technology and Design. His research areas include Computer Science Education.

### CURRICULUM SPECIALIST



### **DR. SCARLETT MATTOLI**

Dr. Scarlett is a Psychotherapist/Counsellor, Coaching Psychologist & Supervisor and Psychometrist, specialising in psychological and therapeutic support.

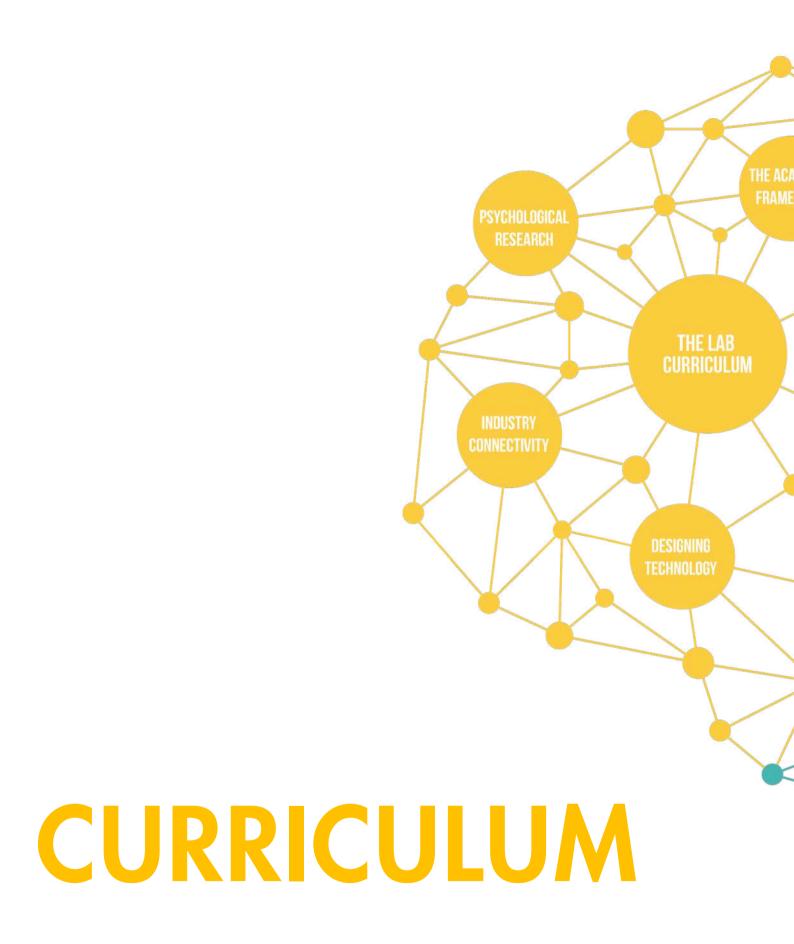
> CHILD PSYCHOLOGIST SPECIALIST

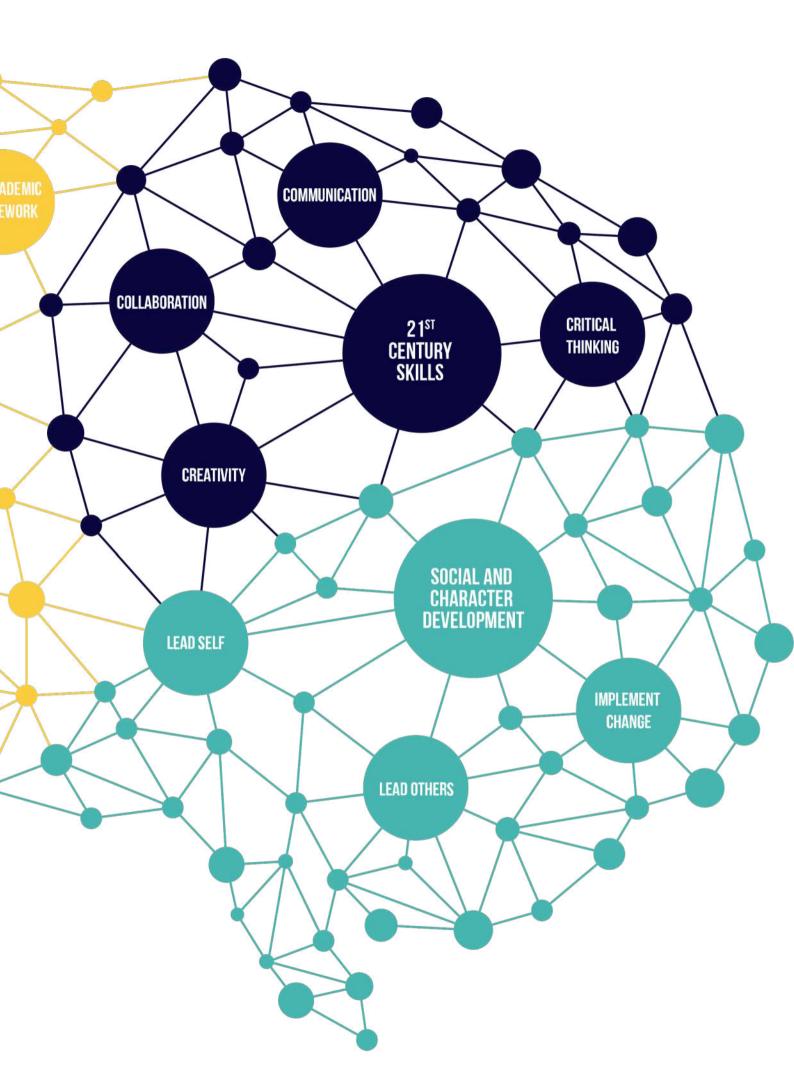


### DR. COLLIN ANG

Dr. Collin is the Managing Director of Decision Science and is a thought leader in the industry for digital transformation and analytics

TECHNOLOGY SPECIALIST





## EMPOWERING

### STUDENTS THROUGH COMPUTATIONAL THINKING





# FOR AGE 5 6 YEARS OLD

Curated for beginners with no Coding background.

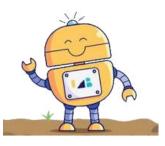
#### A screen free curriculum!

Stresses on cultivating the right habits in the use of technology to students at an early age.

### Program Outline

- Classroom-based structure
- A Half Year Foundation Program
- 2 terms of 10 weekly lessons
- Fuses Coding with multiple disciplines
- Ratio 1:4
- Duration 90 mins

JOIN US FOR A FUN-FILLED LEARNING EXPERIENCE!



| Week | Торіс   | STEM Concept(s)  | Building                      |
|------|---|--|-------------------------------|
| 1    | Introduction to<br>Lego building<br>and Counting                  | Counting with large<br>numbers                               | Structures that spin          |
| 2    | Measure<br>Distance by<br>Counting                                | Measurement by<br>Counting                                   | Movable vehicles              |
| 3    | Repeated<br>Actions   | Introduction of Loops  | Objects that<br>require gears |
| 4    | Directions  | Directions (Left and<br>Right)                               | An insect that<br>crawls      |
| 5    | Understanding<br>Loops through<br>Pattern<br>Recognition          | Pattern Recognition  | An animal that is fierce      |
| 6    | Relational<br>Directions  | Understanding<br>directions in relation<br>to something      | A vehicle with<br>wheels      |
| 7    | Understanding Maps  | Location   | A fun carnival ride           |
| 8    | Map Reading<br>Skills by<br>following<br>multiple<br>instructions | Coordinates  | A space satellite             |
| 9    | Mental Rotation   | Mental<br>representations of<br>multi-dimensional<br>objects | A flying machine              |
| 10   | Final Project   |  |                               |



FOUNDATION TERM 1







| Week | Торіс  | STEM Concept(s)                                   | LEGO Building<br>Problem Statement                    |
|------|--|---|---|
| 1    | Measure<br>Distance by<br>Estimating             | Estimating<br>distances                           | A robot that helps<br>seniors                         |
| 2    | Pattern<br>Recognition<br>through<br>Observation | Pattern<br>Recognition<br>Loops                   | A robot that helps<br>humans to<br>denotate landmines |
| 3    | Visualizing<br>Directions                        | Visualization Skills<br>Directions                | A robot that<br>reaches high places                   |
| 4    | Map Reading<br>with Coordinates                  | Map Reading<br>Coordinates                        | A home cleaning<br>robot                              |
| 5    | Mental Rotation<br>with 2D                       | Mental<br>representations of<br>two-dimensional   | A robot that can<br>navigate dangerous<br>places      |
| 6    | Mental Rotation<br>with 3D                       | Mental<br>representations of<br>three-dimensional | A robotic arm   |
| 7    | Decomposition                                    | Breaking<br>problems into<br>smaller ones         | A robot that<br>explores other<br>planets             |
| 8    | Troubleshooting                                  | Problem Solving<br>skills                         | A robot that serves customers                         |
| 9    | Debugging  | Finding errors and solving them                   | A robot that makes deliveries                         |
| 10   |  | Final Project                                     |   |



FOUNDATION TERM 2





# CORE FOR AGE 5 6 YEARS OLD

Introductory course to the world of technology and programming

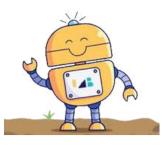
Built upon the MOE Primary 1 Math syllabus

Promotes Computational Thinking through play

### Program Outline

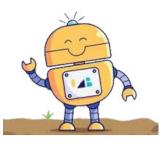
- Classroom-based structure
- A Full Year Foundation Program
- 4 terms of 10 weekly lessons
- Fuses Coding with multiple disciplines
- Ratio 1:4
- Duration 90 mins

JOIN US FOR A FUN-FILLED LEARNING EXPERIENCE!



| Week | Торіс  | Math/Science<br>Concept   | Tech/Eng Concept   |
|------|--|---|--|
| 1    | Introduction to<br>Robots and Coding                     | Components of a robot   | LEGO Build and<br>Code: Vehicle  |
| 2    | Electric Circuits and<br>Electrical<br>Conductivity      | Electric Circuit<br>identification and<br>Classification of<br>objects with and<br>without electrical<br>conductivity | Manipulation of Snap<br>Circuits<br>Manipulation of LED<br>Matrix through Coding |
| 3    | Numbers to 10<br>Programming:<br>Events and<br>Sequence  | Numbers to 10   | Event and Sequence<br>Gyro Sensor<br>Buzzer                                      |
| 4    | Ordinal Numbers<br>and Pattern<br>Recognition            | Ordinal Numbers<br>(Positions to 6th)<br>Time<br>Speed  | Manipulation of<br>Motors<br>Pattern Recognition<br>through grouping             |
| 5    | Math Operators<br>Programming:<br>Events and<br>Sequence | Greater/Lesser Than<br>Loudness (i.e.<br>Frequency)   | Event and<br>Sequence<br>Voice Sensor<br>Gyro Sensor                             |
| 6    | Moments  | Moments -<br>Clockwise and Anti-<br>clockwise   | LEGO Build and<br>Code: Fishing Rod  |
| 7    | Motor Manipulations<br>with Angles, Power<br>and Speed   | Angles<br>Power<br>Speed  | Manipulation of<br>Motors  |
| 8    | Positive and<br>Negative Numbers                         | Subtraction within 10<br>and Negative<br>numbers  | LEGO Build and<br>Code: A Crocodile<br>Jaw                                       |
| 9    | Additions to 10 and<br>Sequence                          | Numbers and<br>Additions to 10  | Sequence<br>Manipulation of Motors<br>LEGO Build and<br>Code: Terminator         |
| 10   | Final Project  |   |  |

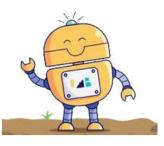




| Week | Topics  | Math/Science<br>Concept  | Tech/Eng Concept   |
|------|---|--|--|
| 1    | Animations  | X Y axis   | LCD Screen   |
| 2    | Fractions<br>Programming:<br>Events and<br>Random                       | Fractions and The<br>Value<br>of Money                                   | Manipulation of<br>Motors<br>Events and Random             |
| 3    | Sequence<br>(Movements)   | Understanding of<br>Angles in Geometry                                   | Sequence<br>Pattern Recognition                            |
| 4    | Subtraction within<br>10<br>Programming:<br>Positive and<br>Negative    | Numbers and<br>Subtraction within 10<br>Positive and Negative<br>Numbers | Manipulation of<br>Motors                                  |
| 5    | Additions and<br>Subtraction within<br>10                               | Concept of Symmetry<br>Mechanism of a<br>Balancing Beam                  | Symmetrical<br>structures with<br>Strawbees                |
| 6    | Sound<br>Programming:<br>Sequence with<br>Sound. Motor and<br>RGB Light | Concept of Sound   | Sequence<br>Touch Sensor                                   |
| 7    | Map Reading<br>Sequence with<br>movement and<br>turns                   | Mapping<br>3D Visualization  | Sequence   |
| 8    | Introduction to Gears   | Gear Ratio<br>Speed  | LEGO Gears   |
| 9    | Remote Controlled<br>Devices and<br>Introduction to<br>Drone            | Map Visualization<br>Aerodynamics of a<br>Drone                          | Technology of a<br>Drone<br>Infra-red<br>Bluetooth<br>Wifi |
| 10   |   | Final Project  | 1  |



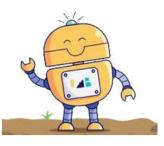




| Week | Topics  | Math/Science<br>Concept                                | Tech/Eng Concept   |
|------|---|--|--|
| 1    | Measuring Force<br>with Touch Sensor                          | Concept of Force<br>Math Operators                     | Touch Sensor<br>Manipulation of<br>Motors                              |
| 2    | Sequencing with<br>Lego Robotics<br>Programming               | Music  | Sequence<br>Lego Build and Code:<br>Racing Car                         |
| 3    | Coding with X and<br>Y in programming<br>world                | X and Y axis   | Using of X and Y axis<br>in Coding                                     |
| 4    | Exploring sensors<br>with Lego Robotics<br>Programming        | Binary Greater/Less<br>Than                            | Touch sensor<br>Ultrasonic sensor<br>Lego Build and Code:<br>Robot Cat |
| 5    | Gears and<br>Sequence   | Gearing  | Sequence<br>Lego Build and Code:<br>Automatic Door                     |
| 6    | Sequencing with<br>Lego Robotics<br>Programming<br>using Time | Concept of Time:<br>Analog vs Digital                  | Sequence<br>Time<br>Lego Build and Code:<br>Terminator                 |
| 7    | Mechanism of a<br>Robot Hand                                  | Mechanics of a Robotic<br>hand                         | Lego Build and Code:<br>Grabber  |
| 8    | Infrared sensor<br>with Codey Rocky                           | Infrared sensor<br>Infrared vs Ultrasonic<br>Proximity | Infrared sensor  |
| 9    | Math Operators<br>with Ultrasonic<br>sensor                   | Math Operators   | Ultrasonic Sensor<br>Lego Build and Code:<br>Robot Cat                 |
| 10   | Final Project   |  |  |







| Week | Topics   | Math/Science<br>Concept   | Tech/Eng Concept  |
|------|--|---|---|
| 1    | Sequencing with<br>Lego Robotics<br>Programming<br>using Speed   | Speed   | Sequence  |
| 2    | 3D Printing with X,<br>Y and Z axis                              | Graphs (X, Y and Z<br>Axis)   | Technology of 3D<br>printing                                    |
| 3    | Learning<br>aerodynamics<br>with Lego<br>Robotics<br>Programming | X and Y axis  | Touch sensor<br>Lego Build and<br>Code: Flying Bird             |
| 4    | Introduction to<br>Augmented<br>Reality                          | Directions  | Technology of<br>Augmented Reality                              |
| 5    | Colour Sensor<br>with Spike Robot                                | Colour<br>Speed<br>Sound  | Colour Sensor   |
| 6    | Concept of Light   | Concept of Light<br>Reflection/Refraction<br>Light Intensity/<br>Luminosity | Colour Sensor<br>Lego Build and<br>Code: Light sensor<br>robot  |
| 7    | Loop and<br>AND/OR operator<br>with Codey Rocky                  | Logic and Pattern<br>Recognition  | AND/OR Operator<br>Loop<br>If-Then Condition                    |
| 8    | Sound and Colour<br>with Lego<br>Robotics<br>Programming         | Sound<br>Colour   | Colour Sensor<br>Touch Sensor<br>Lego Build and<br>Code: Camera |
| 9    | Introduction to<br>Virtual Reality                               |   | Technology of<br>Virtual Reality<br>Gyro Sensor                 |
| 10   | Final Project  |   |   |







### COMMIT TO A YEARLY MEMBERSHIP & GET PROMOTIONAL RATES!

10 Classes

\$650 (\$65/class)

40 Classes

\$2,400 (\$60/class)

\*\* Registration fee is \$80 per student

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